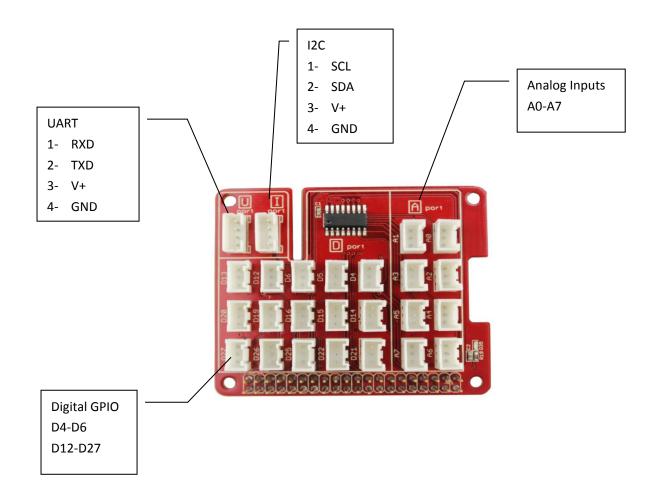
# **Crowtail- Base Shield for Raspberry Pi**

This is a Crowtail base shield for Raspberry Pi with UART/I2C/Analog/Digital interface. All the Crowtail modules can be plugged onto Raspberry Pi through this base shield. Moreover, this shield has an on-board ADC chip so that analog output modules can be used on Raspberry Pi. The ADC chip used is MCP3008. It talks to Raspberry Pi using SPI interface.







## Control the analog inputs through the MCP3008

#### Installation of the needed modules

An actual Raspbian OS-Image (Debian Wheezy) is a good choice. First of all we've to activate the SPI-Interface of the Raspberry Pi, to make the communication with the ADC of the shield possible. For this, we're starting with the following command:

```
sudo raspi-config
```

Choose "Advanced Options" when you see this window,

Then we click "A6 SPI"

```
Al Overscan
A2 Hostname
Set the visible name for this Pi on a network
A3 Memory Split Change the amount of memory made available to the GPU
A4 SSH
A5 Device Tree
A6 SPI
Enable/Disable butomatic loading of SPI kernel module (needed for e.g. PIFace)
A7 I2C
Bnable/Disable automatic loading of I2C kernel module
A8 Serial
Enable/Disable shell and kernel messages on the serial connection
A9 Audio
Force audio out through HDMI or 3.5mm jack
A0 Update

Select>

Select>

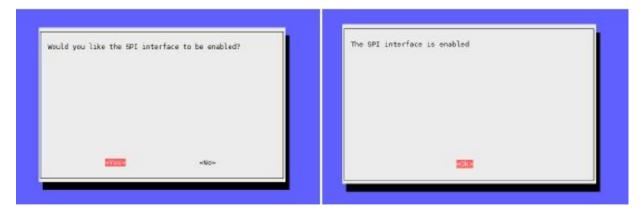
Select>

A8 Serial

A9 Audio

Force audio to the latest version
```

The next two windows have to be accepted with "Yes" and "OK"



Also the next two ones...



Finally we click "Finish" to close this Configuration Tool...

...and reboot the Raspberry Pi with the following command:

```
sudo reboot
```

After the reboot, we need to load and install the needed Drivers and Modules. The Raspberry Pi need to be connected to the Internet first in this step- put the following commands in the console of the Raspberry Pi and confirm each with press on [Enter].:

sudo apt-get update

sudo apt-get install python-imaging python-imaging-tk python-pip python-dev git

sudo pip install spidev

sudo pip install wiringpi

At last you have to reboot it again:

sudo reboot

Python-Example for using the MCP3008 ADC Controller - testadc.py

```
import spidev
import time
import sys
spi = spidev.SpiDev()
spi.open(0,0)
def readadc(adcnum):
 if adcnum >7 or adcnum <0:
   return-1
  r = spi.xfer2([1,8+adcnum << 4,0])
 adcout = ((r[1] &3) <<8)+r[2]
 return adcout
while True:
  if len(sys.argv) >1:
  for i in range(len(sys.argv)):
   if i == 0:
    print "_
                                                       _\n"
   else:
   adc_channel = int(sys.argv[i])
    print "Channel" + str(adc_channel)
    value=readadc(adc_channel)
   volts=(value*3.3)/1024
   print("%4d/1023 => %5.3f V" % (value, volts))
   print "
  print "
                                                      _\n"
  time.sleep(1.5)
  else:
  print "
                                                      _\n"
  print "Channel 0"
  value=readadc(0)1
  volts=(value*3.3)/1024
  print("%4d/1023 => %5.3f V" % (value, volts))
  print "Channel 1"
  value=readadc(1)
  volts=(value*3.3)/1024
  print("%4d/1023 => %5.3f V" % (value, volts))
  print "Channel 2"
  value=readadc(2)
  volts=(value*3.3)/1024
  print("%4d/1023 => %5.3f V" % (value, volts))
  print "Channel 3"
  value=readadc(3)
  volts=(value*3.3)/1024
  print("%4d/1023 => %5.3f V" % (value, volts))
  print "Channel 4"
   value=readadc(4)
  volts=(value*3.3)/1024
  print("%4d/1023 => %5.3f V" % (value, volts))
  print "Channel 5"
  value=readadc(5)
  volts=(value*3.3)/1024
  print("%4d/1023 => %5.3f V" % (value, volts))
  print "Channel 6"
  value=readadc(6)
  volts=(value*3.3)/1024
  print("%4d/1023 => %5.3f V" % (value, volts))
  print "Channel 7"
  value=readadc(7)
  volts=(value*3.3)/1024
  print("%4d/1023 => %5.3f V" % (value, volts))
  print "_
  time.sleep(1.5)
```

The file "testadc.py" shows how to measure analog voltage level with a python script: with the function readadc() and a specified Channel (0-7) you can read out the actual value. Create a new file with the name "testadc.py" and copy the script shown above in this file (please make sure that you don't miss any spaces).

The script can be used in two different ways now:

#### Output the values of all ADC-Channels simultaneously:

```
sudo python testado.py
```

This command causes that the values of all ADC-Channels be read out and displayed every 1.5s.

```
Channel 0
513/1023 => 1.653 V
Channel 1
519/1023 => 1.673 V
Channel 2
0/1023 => 0.000 V
Channel 3
0/1023 => 0.000 V
Channel 4
0/1023 => 0.000 V
Channel 5
0/1023 => 0.000 V
Channel 6
0/1023 => 0.000 V
Channel 6
0/1023 => 0.000 V
Channel 7
0/1023 => 0.000 V
```

### **Output of values from specific Channels:**

```
sudo python testado.py 3 7
```

You can also read out the values from individual channels – specify them with their channel number directly after the command, and you should to click the space key to separate this two commands.

In this example this would be the channels [3] and [7]

```
Channel 3
518/1023 => 1.669 V

Channel 7
1/1023 => 0.003 V
```